

Standard specifications

RS007NFF60

December 05, 2017

KAWASAKI HEAVY INDUSTRIES, LTD. ROBOT DIVISION

 Specification :
 90101-2728DEB

 (Arm) :
 90151-0206DEB

 (Controller) :
 90152-0048DEB

[1] Robot Arm								
1. Model	RS007N							
2. Type	Articulated robot							
3. Degree of freedom	6 axes							
4. Axis specification	Operating axis Max. operating range			nge	Max. speed			
	Arm rotation (JT1)		+180 ° ~−180 °		470 °/s			
	Arm out-in	(JT2)	$+135^{\circ}$ $\sim-135^{\circ}$		380 °/s			
	Arm up-down (JT3		$+155^{\circ} \sim -155^{\circ}$		520 °/s			
	Wrist swivel	Wrist swivel (JT4) $+200^{\circ} \sim -200^{\circ}$		00 °	550 °/s			
	Wrist bend	(JT5)	+125 ° ~-125 °		550 °/s			
	Wrist twist	(JT6)	+360 ° ~−360 °		1000 °/s			
5. Repeatability	± 0.02 mm (at the tool mounting surface)							
6. Max. payload	7 kg							
7. Max. speed	12100 mm/s (at the center of tool mounting surface)							
8. Load capacity of wrist								
		M	ax. torque	M	oment of inertia*			
	JT4		17.0 N·m		0.50 kg·m2			
	JT5		17.0 N·m		0.50 kg·m2			
	JT6		10.0 N·m		0.20 kg·m2			
	Note* Each value in this table shows allowable moment of inertia of JT4/JT5/JT6 when max. allowed torque is applied to each axis. If more detailed data is required for your application, please contact Kawasaki.							
9. Driving motor	Brushless AC Servomotor							
10. Working range	See attached drawing							
11. Mass	35 kg (without options)							
12. Color	Munsell 10GY9/1 equivalent							
13. Installation	Floor or Ceiling mounting							
14. Environment cond.	(Temperature) $0 \sim 45$ °C, (Humidity) $35 \sim 85$ %, no dew, nor frost allowed							
15. Degree of protection	Wrist: IP67 Arm: IP65							
16. Built-in utilities	Pneumatic pipings	s (ϕ 6 × $\overline{1}$ line	es), LAN harness(CAT	75e, straight	<u></u>			
17 Options								
Sensor harness	8 circuits							
Built-in valves	Double solenoid/ Single solenoid valves (3 units max.)							
Pneumatic circuit	Air cleaning equipment (filter, regulator, mistseparator)							
Adjustable mechanical	ers							
stoppers								
Adapter plate								
Arm installation stand	stallation stand Height 600 mm, 300 mm							
Arm installation plate								
18. Others Consult Kawasaki about maintenance parts and spare parts.								

[2] (Controller							
1.	Model	F60						
2.	Enclosure	Protection level: IP20 Open structure / Direct cooling system *1						
_	Dimensions	See attached drawing						
	Number of controlled	Max.8 axes (standard 6 axes, option 2 axes)						
	axes	Carried & Mico, option 2 Mico,						
5.	Servo control and	Full Digital Servo System						
	drive system							
6.	Type of control	Teach mode Joint, Base, Tool, Fixed Tool (option) operation mode Repeat mode Joint, Linear, Circular (option) interpolation						
7.	Teaching method	Teaching or AS language programming						
	Memory capacity	16 MB						
9.	External operation	External Emergency stop, External Hold, etc.						
	signals							
10.	Number of	2 slots						
	Option board slots							
	Operation panel	Teach/Repeat SW, Emergency Stop SW						
12.	Communication I/F	Ethernet	GE #W/10D + 65 5	2port				
		(1000BASE-T/100BASE-TX/10BASE-T)						
		USB2.0		3port				
12	M	RS-232C 2port						
	Mass Power requirement	See attached drawing						
14.	Power requirement	AC200 V - AC230 V±10%, 50/60 Hz, 1 phases,						
1.5	Ground	Max. 2.0 kVA Less than 100 Ω (robot dedicated ground)						
13.	Gioulia	Less than 100 t2 (robot dedicated ground) Leakage current: max. 100 mA						
16	Ambient temperature	Leakage current: max. 100 mA 0 - 45°C						
	Relative humidity	35 - 85 % (non-condensation)						
	Color	Munsell: 5Y8.5/1 equivalent						
	Teach Pendant	TFT color display (5.7 inch LCD) with touch panel						
		Emergency Stop SW, Teach Lock SW and Enable SW						
20.	Safety Circuit	Category: 4, Performance Level: e (EN ISO13849-1) *2						
	Number of General	IN:16 OUT:16						
	purpose I/O signals	with an I/O connector. (50pin with cover)						
22.	Standard Options							
	TP sheet language							
	Power/Signal cable	5m, 10m, 15m						
	Teach Pendant cable	5m, 10m, 15m						
23.	Other Options							
	Number of additional	Inside Controller		oard(IN:32 OUT:32) ···up to 2 boards				
	I/O signals	Remote I/O		te I/O unit(IN:32 OUT:32) ···up to 4 units				
		Total max I/O number		8 OUT:128				
	Intake Filter		Dusts more than 1mm diameter do not get into the controller from intake FAN					
	Enclosure			re / Indirect cooling system (Ambient temperature 0 - 45 °C) *3				
	Motor brake release	Manual brake release switch BOX						
	PC cable (RS-232C)	1.5 m, 3 m						
	External axes control	Additional amplifier and harnesses for external axes						
	Extended safety functions	,	Cubic-S(Motion area monitoring, Joint monitoring, Speed monitoring etc.) *3					
1	Teach Pendant option		Connector for TP less					
	Fast check mode	Fast check mode Switch						
	Others Field BUS, Software PLC, Analog input/output, Conveyor Synchronization, Bluetooth							
24.	4. Others Consult Kawasaki about maintenance parts and spare parts.							
			. 1					

NOTE*1

Cooling of the electronic components in this open construction F60 controller is achieved by circulation of ambient air.

The enclosure is designed to protect personnel from coming in contact with hazardous parts inside the controller.

There is no protection to less than 10 mm of alien substance and water.

Please consider $\ensuremath{\textcircled{1}}\ensuremath{\textcircled{2}}$ and $\ensuremath{\textcircled{3}}$ and select the option about protection to the environmental specification

- ①There is no or few non-conductive dusts & particles(influence for the controller is little) · · · Option is not needed.
- There is high possibility that non-conductive dusts & particle will get into controller. Select the option intake Filter or Enclosed structure
- ③There is high possibility that conductive dusts & particle will get into controller. ····Select the option Enclosed structure

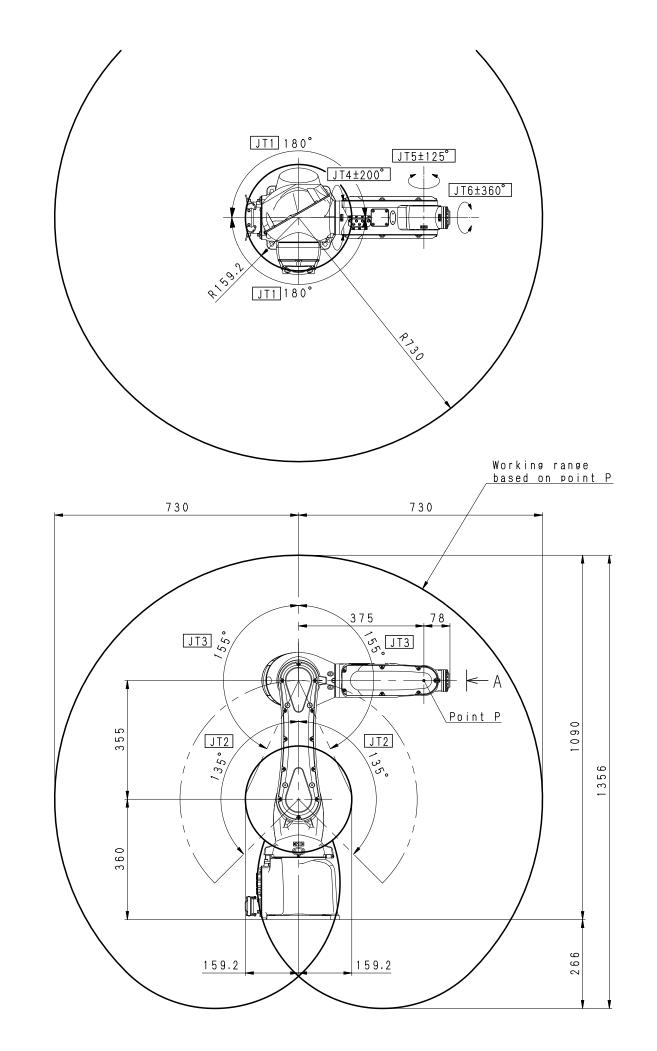
NOTE*2

Category and Performance level (PL) are determined by the whole system and conditions.

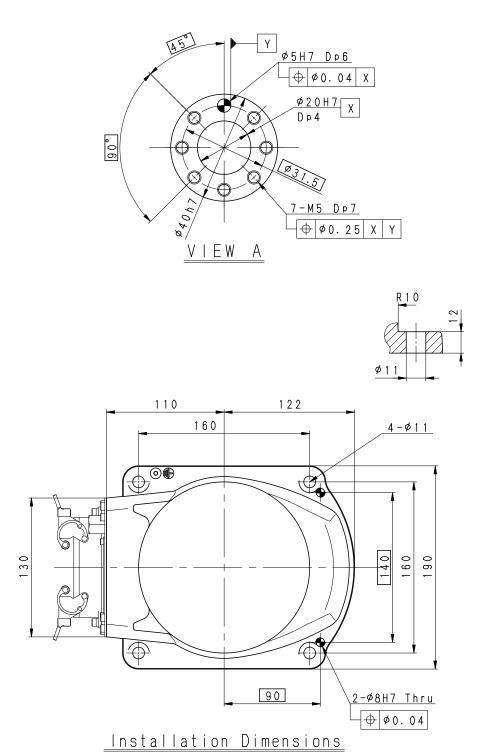
The safety circuit of this controller is available in the system of category: up to 4, PL: up to e.

NOTE*3

Attaching additional unit makes size of a controller larger.



148.7 170

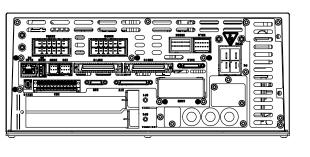


RSOO7N-A WORKING RANGE

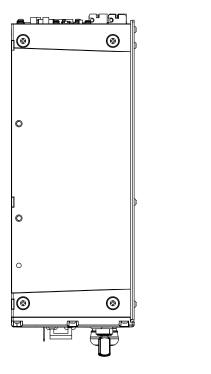


F60 CONTROLLER

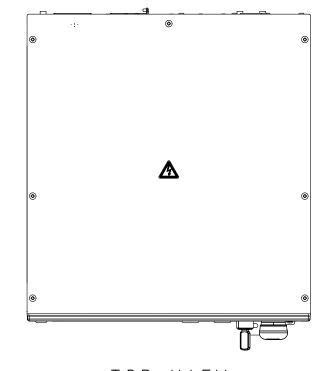
MASS: 8. 3 Kg (Without any options)



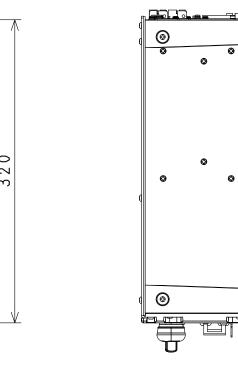
REAR VIEW



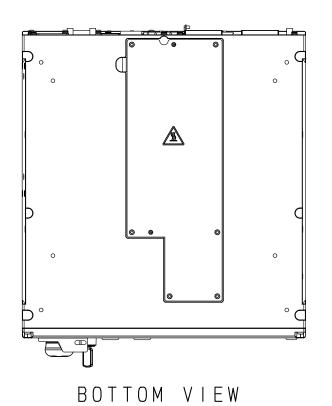
SIDE VIEW



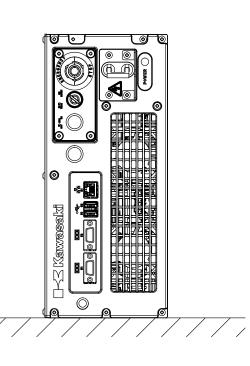
TOP VIEW

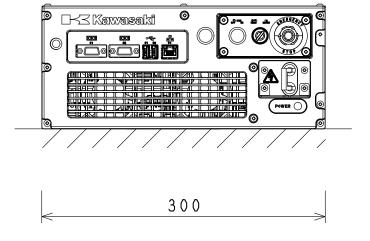


SIDE VIEW

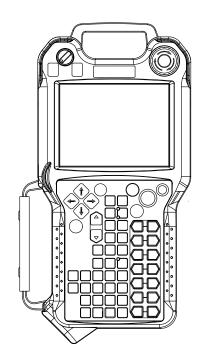


Vertical Mount

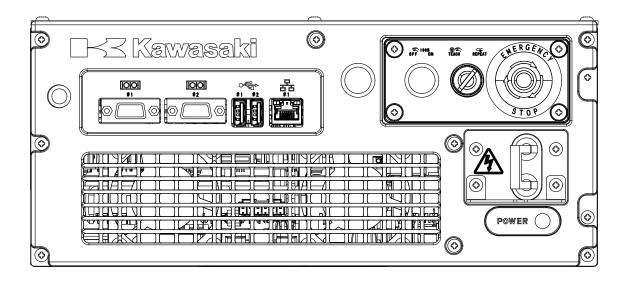




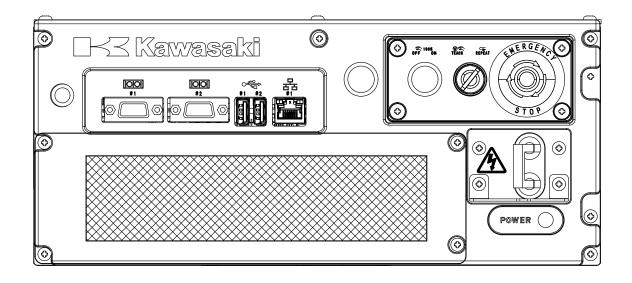
FRONT VIEW



O O pen Structure Standard



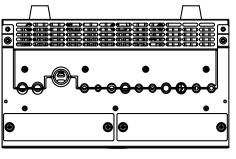
②Open Structure With Intake Filter



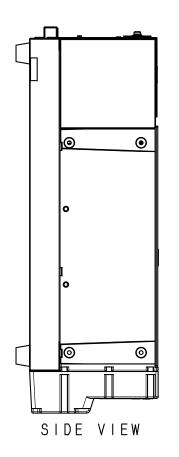
F60 CONTROLLER

MASS: 16Kg

(With Enclosed Structure option)



REAR VIEW



Vertical Mount

