

Standard specifications

RS006LFF60

1st Edition: January 12, 2017 2nd Edition: July 31, 2017 3rd Edition: May 10, 2018

> KAWASAKI HEAVY INDUSTRIES, LTD. ROBOT DIVISION

Specification:	90101-2622DEC
(Arm):	90151-0046DEB
(Controller):	90152-0048DEB

1. Specification of Robot

[1] Robot Arm						
1. Model	RS006L-A					
2. Type	Articulated robot					
3. Degree of freedom	6 axes					
4. Axis specification	Operating axis	Max. operating range	e Max. speed			
	Arm rotation (JT1)					
	Arm out-in (JT2)	+145 ° ∼−105 °	250 °/s			
	Arm up-down (JT3) $+150^{\circ} \sim -163^{\circ}$		215 °/s			
	Wrist swivel (JT4)	+270° ∼−270°	365 °/s			
	Wrist bend (JT5)	+145° ∼-145°	380 °/s			
	Wrist twist (JT6)	+360° ∼−360°	700 °/s			
5. Repeatability	± 0.03 mm (at the tool mounting surface)					
6. Max. payload	6 kg					
7. Max. speed	13700 mm/s (at the center of	tool mounting surface)				
8. Load capacity of						
wrist	N	lax. torque	Moment of inertia*			
	JT4	13 N·m	$0.45 \text{ kg} \cdot \text{m}^2$			
	JT5	13 N·m	$0.45 \text{ kg} \cdot \text{m}^2$			
	JT6	7.5 N⋅m	0.14 kg·m²			
	Note* Each value in this table	e shows allowable momen				
	Note* Each value in this table shows allowable moment of inertia of JT4/JT5/JT6 when max. allowed torque is applied to each axis. If more detailed data is required for					
	your application, please contact Kawasaki.					
9. Driving motor	Brushless AC Servomotor					
10. Working range	See attached drawing					
11. Mass	150 kg (without options)					
12. Color	Munsell 10GY9/1 equivalent					
13. Installation	Floor or Ceiling mounting					
14. Environment cond.	(Temperature) $0 \sim 45$ °C, (Humidity) $35 \sim 85$ %, no dew, nor frost allowed					
15. Degree of protection	Wrist: IP67 Arm: IP65					
16. Built-in utilities	Pneumatic pipings (ϕ 8 × 2 lines)					
17. Options	Wall mounting installation					
	Degree of protection of arm: IP67					
	Sensor harness (12 circuits), wired inside robot arm					
	Double solenoid/ Single solenoid valves (4 units max.)					
	Air cleaning equipment (filter, regulator, mistseparator)					
	Adjustable mechanical stoppers JT1/JT2/JT3					
	Color (Munsell)					
	Traverse unit (Stroke mm)					
	Arm installation stand (height 600 mm, 300 mm) Arm installation plate (750 mm × 750 mm)					
10 Othors						
18. Others	Consun Nawasaki about mannenance parts and spare parts.					

[2] (Controller				
1.	Model	F60			
2.	Enclosure	Protection level: IP20 Open structure / Direct cooling system *1			
_	Dimensions	See attached drawing			
	Number of controlled	Max.8 axes (standard 6 axes, option 2 axes)			
	axes	Than o area (standard o area, option 2 area)			
5.	Servo control and	Full Digital Servo Sys	stem		
	drive system				
6.	Type of control	Teach mode Joint, Base, Tool, Fixed Tool (option) operation mode			
		Repeat mode Joint, Linear, Circular (option) interpolation			
7.	Teaching method	Teaching or AS language programming			
	Memory capacity	16 MB			
9.	External operation	External Emergency stop, External Hold, etc.			
	signals				
10.	Number of	2 slots			
	Option board slots				
	Operation panel	Teach/Repeat SW, En	nergency Stop SV		
12.	Communication I/F	Ethernet	OF TWATER	2port	
		(1000BASE-T/100BA	SE-TX/10BASE-		
		USB2.0		3port	
12	M	RS-232C		2port	
	Mass Power requirement	See attached drawing	100/ 50/60 Hz	1 who coo	
14.	Power requirement	AC200 V - AC230 V±10%, 50/60 Hz, 1 phases,			
1.5	Ground	Max. 2.0 kVA			
13.	Giouila	Less than 100 Ω (robot dedicated ground)			
16	Ambient temperature	Leakage current: max. 100 mA 0 - 45 °C			
	Relative humidity	0 - 45 C 35 - 85 % (non-condensation)			
	Color	Munsell: 5Y8.5/1 equivalent			
	Teach Pendant	TFT color display (5.7 inch LCD) with touch panel			
		Emergency Stop SW, Teach Lock SW and Enable SW			
20.	Safety Circuit	Category: 4, Performa			
	Number of General	IN:16 OUT:16	`	,	
	purpose I/O signals	with an I/O connector. (50pin with cover)			
22.	Standard Options				
	TP sheet language	English or Japanese or Chinese			
	Power/Signal cable	5m, 10m, 15m			
	Teach Pendant cable	5m, 10m, 15m			
23.	Other Options		1		
	Number of additional	Inside Controller		oard(IN:32 OUT:32) ···up to 2 boards	
	I/O signals	Remote I/O		ote I/O unit(IN:32 OUT:32) ···up to 4 units	
		Total max I/O number		28 OUT:128	
	Intake Filter			get into the controller from intake FAN	
	Enclosure			are / Indirect cooling system (Ambient temperature 0 - 45 °C) *3	
	Motor brake release	Manual brake release	switch BOX		
	PC cable (RS-232C)	1.5 m, 3 m			
	External axes control	Additional amplifier and harnesses for external axes			
1	Extended safety functions	Cubic-S(Motion area monitoring, Joint monitoring, Speed monitoring etc.) *3			
	Teach Pendant option		Connector for TP less		
	Fast check mode	Fast check mode Switch			
	Others	Field BUS, Software PLC, Analog input/output, Conveyor Synchronization, Bluetooth			
24.	Others Consult Kawasaki about maintenance parts and spare parts.				
		•	<u> </u>	-	

NOTE*1

Cooling of the electronic components in this open construction F60 controller is achieved by circulation of ambient air.

The enclosure is designed to protect personnel from coming in contact with hazardous parts inside the controller.

There is no protection to less than 10 mm of alien substance and water.

Please consider $\ensuremath{\textcircled{1}}\ensuremath{\textcircled{2}}$ and $\ensuremath{\textcircled{3}}$ and select the option about protection to the environmental specification

- ①There is no or few non-conductive dusts & particles(influence for the controller is little) · · · Option is not needed.
- There is high possibility that non-conductive dusts & particle will get into controller. Select the option intake Filter or Enclosed structure
- ③There is high possibility that conductive dusts & particle will get into controller. ····Select the option Enclosed structure

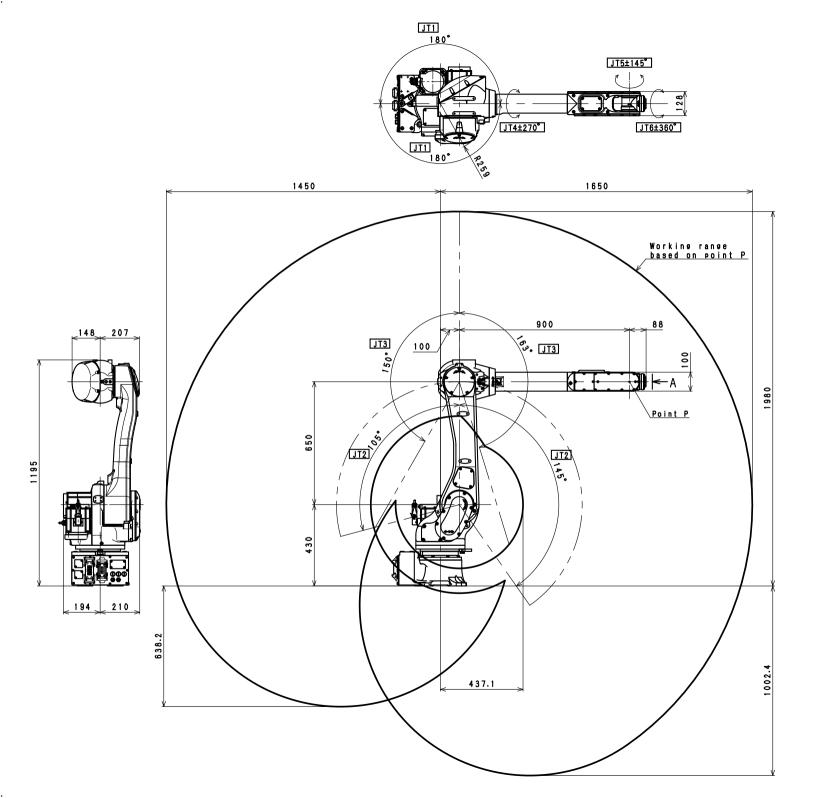
NOTE*2

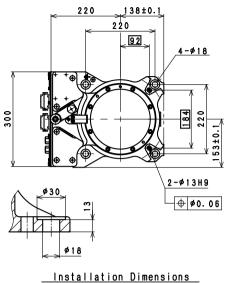
Category and Performance level (PL) are determined by the whole system and conditions.

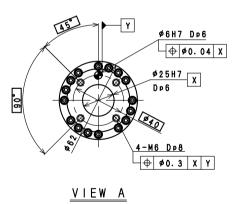
The safety circuit of this controller is available in the system of category: up to 4, PL: up to e.

NOTE*3

Attaching additional unit makes size of a controller larger.



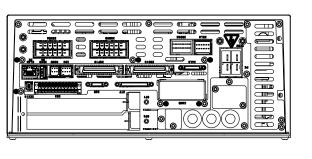




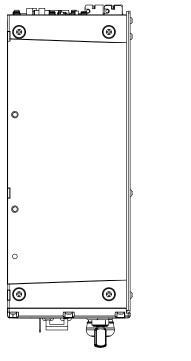
RSOO6L WORKING RANGE

F60 CONTROLLER

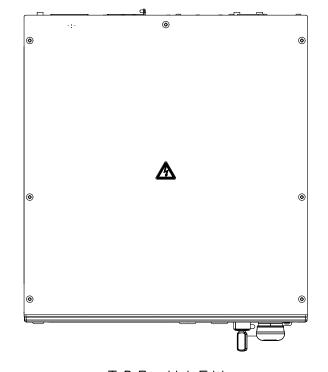
MASS: 8. 3 Kg (Without any options)



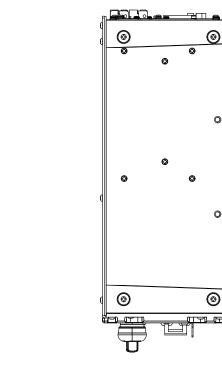
REAR VIEW



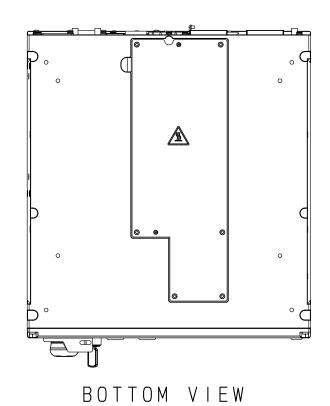
SIDE VIEW

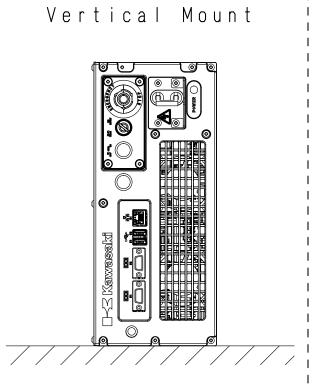


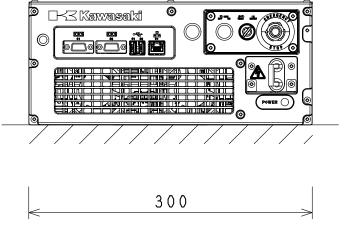
TOP VIEW



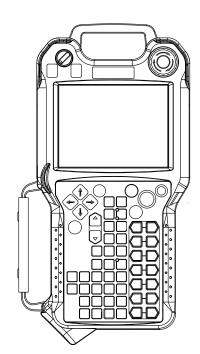
SIDE VIEW



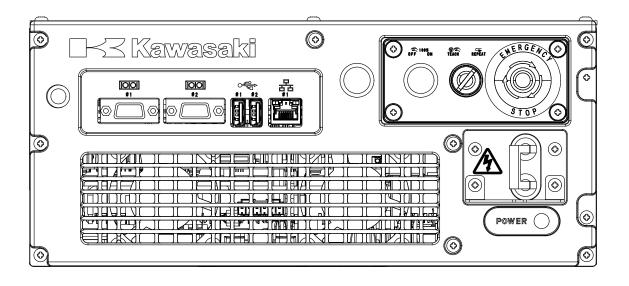




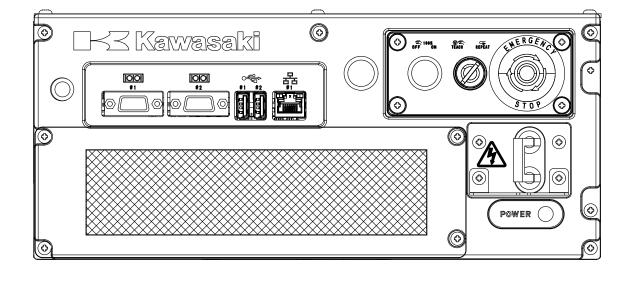
FRONT VIEW



O O pen Structure Standard



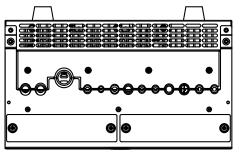
②Open Structure With Intake Filter



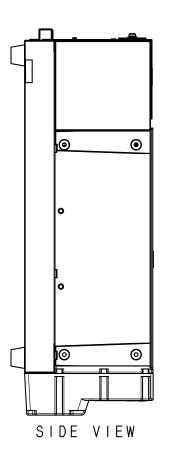
F60 CONTROLLER

MASS: 16Kg

(With Enclosed Structure option)



REAR VIEW



Vertical Mount

TOP VIEW

